

## Full Paper Title in Title Case

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### Extended Abstract

It is expected that authors will submit carefully written and proofread material. Careful checking for spelling and grammatical errors should be performed. These submissions should be around *500 words* and must give a clear indication of the objectives, scope, and results (if available) of the research. No figures or tables are allowed. Presentation for these submissions are limited to 10 minutes (if oral) or poster.

Few references are permitted. The IEEE citation format is used. Books and book chapters should be referenced as [1] and [2] respectively. Patents are referenced based on [3] and a thesis can be referenced as [4]. Finally, conference presentations/papers and journal papers need to be reference based on [5] and [6] respectively.

With the increasing availability of useful information that can be found on the internet, website references must also be reported based on [7]. Meanwhile, due to the dynamic nature of web pages and the fact that in most cases the information is not peer-reviewed, the use of published resources are very much preferred and advised over online references.

The reference section at the end of the paper should be edited based on the following:

### References

- [1] B. Klaus and P. Horn, *Robot Vision*. Cambridge, MA: MIT Press, 1986.
- [2] L. Stein, Random patterns, in *Computers and You*, J. S. Brake, Ed. New York: Wiley, 1994, pp. 55-70.
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- [5] U. V. Koc and K. R. Liu, Discrete-cosine/sine-transform based motion estimation, in *Proceedings of the IEEE International Conference on Image Processing*, Austin, TX, 1994, vol. 3, pp. 771-775.
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